



Volume Delineation: Methods to use

T. Weitzel



Volume Delineation

Volume ??

Volume !

Implicit assumptions:

- some **inside**
- some **outside**
- some **surface**

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Needs **criterion** to distinguish inside from outside

e.g.: „**inside the skull**“

geometric argument, very well defined surface,
but not a simple criterion describing the things inside

b.t.w.: Are the eyes “inside” the skull ?

Volume !

Implicit assumptions:

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Needs **criterion** to distinguish inside from outside

e.g.: „**compact object with high X-ray attenuation**“

Simple, single valued, measurable property.

Threshold value defines points that are inside.



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Simple, single valued, measurable property.

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Example: Two threshold values allow to distinguish
 $D(\text{bone}) > T_1 > D(\text{markers}) > T_2 > D(\text{towel})$

Volume !

Implicit assumptions:

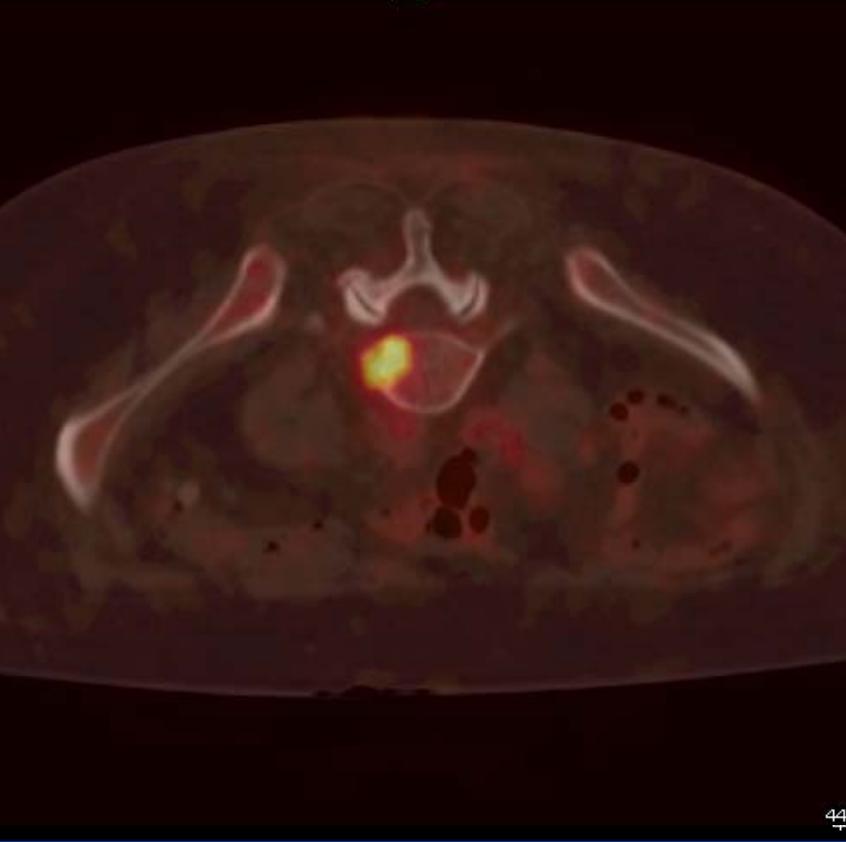
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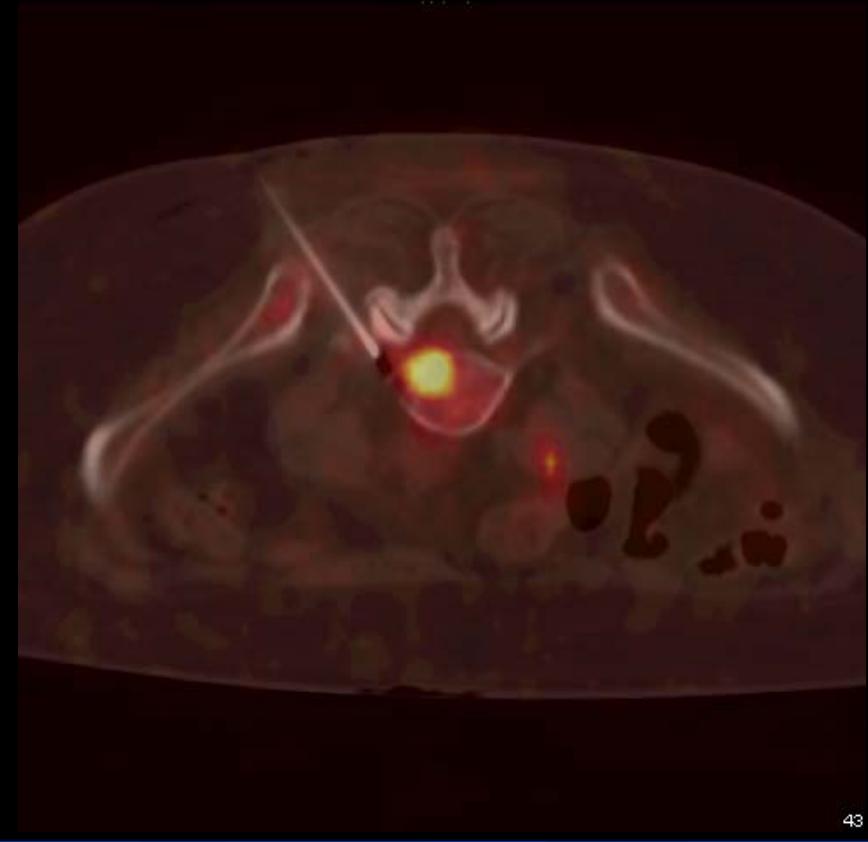
e.g.: „**higher accumulation of FDG**“ (PET)

Single threshold value defines points that are inside.

Method of measurement has to be very well defined:
A Time-Activity-Curve and other parameters are involved.



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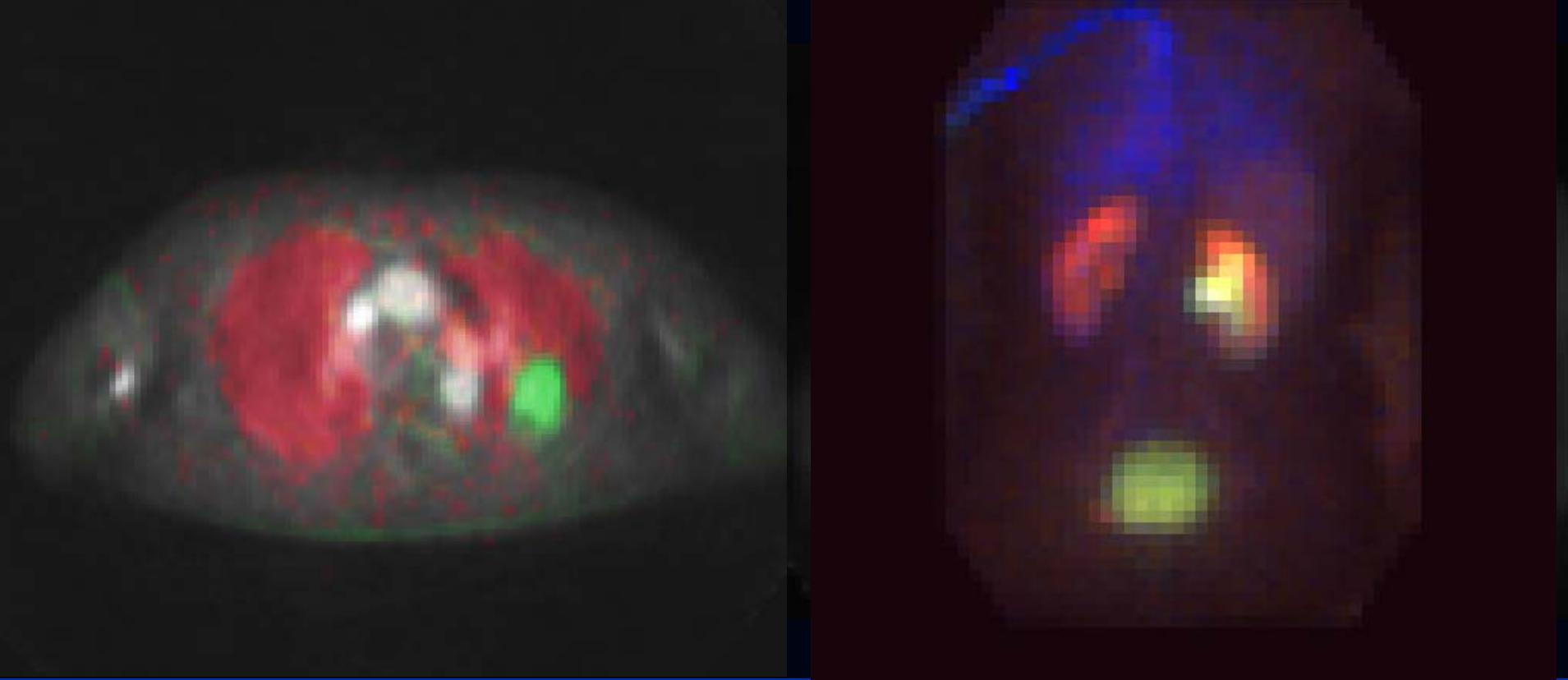
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e.g.: „**characteristic properties of TAC**“ (PET)

Points whose measured Time-Activity-Curve shows certain properties are regarded inside.

There is a indefinite range of mathematical possibilities to describe and evaluate such properties.



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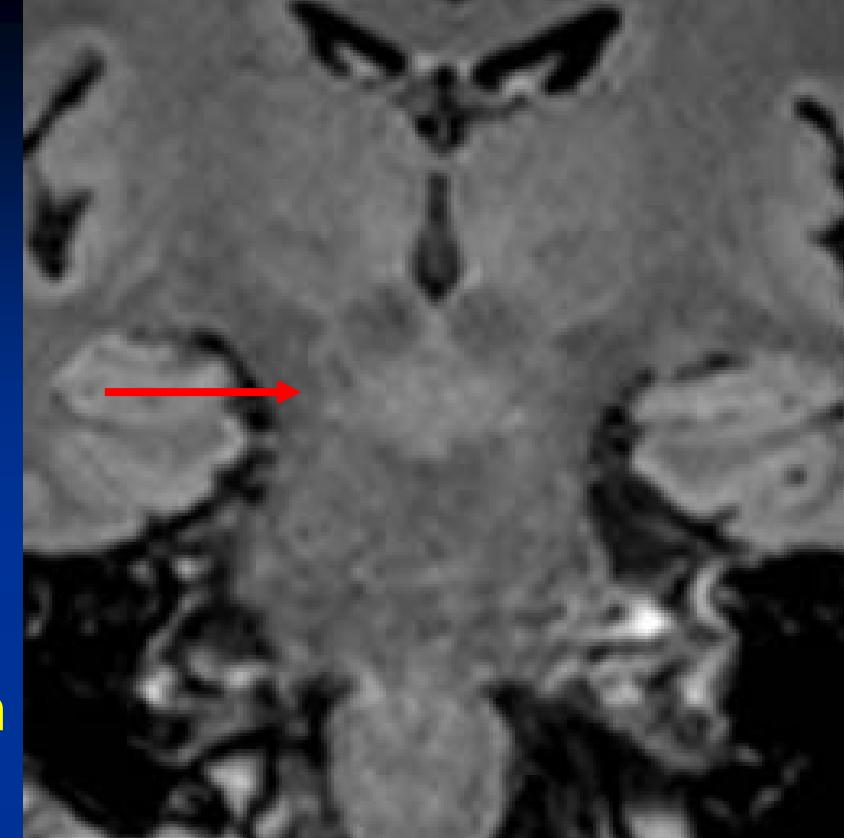
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Needs **criterion** to distinguish inside from outside

e.g.: „**Multi-modal imaging**“ („multi-spectral“ MRI)

Points show a vector of measured values.

There is a indefinite range of mathematical possibilities to define properties in a multidimensional vector-space.



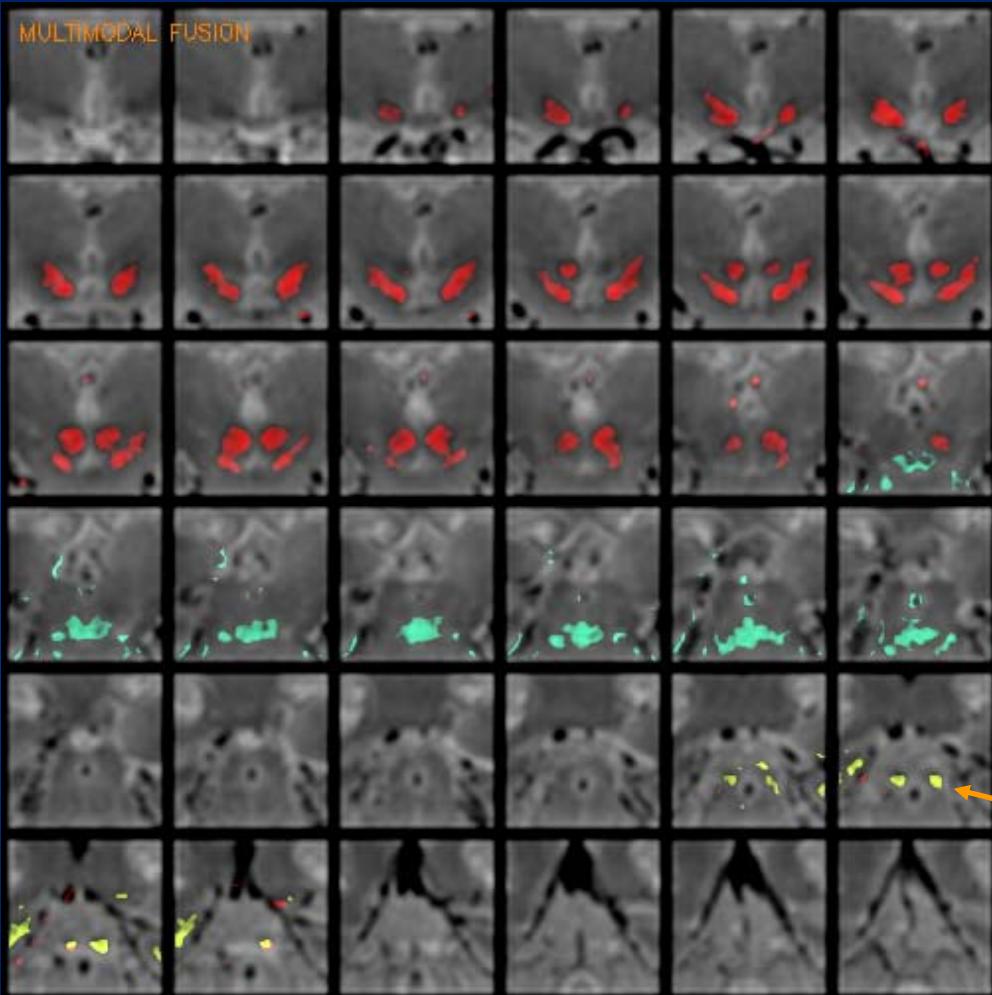
distinguish

e.g.: „Multi-modal imaging“ („multi-spectral“ MRI)

Points show a vector of measured values.

There is an indefinite range of mathematical possibilities to define properties in a multidimensional vector-space.

Volume Delineation



36 slices
nucleus subthalamicus
 $40\text{mm} \times 40\text{mm} \times 1\text{mm}$
1mm slice to slice
substancia nigra

nucleus ruber
brachium conjunctivum
measured values.
nucleus tegmenti
of mathematical possibilities
(PPN) multidimensional (?) vector-space.

6D vector measured for each voxel by using different pulse sequences
not quite sure, because never seen before in MRI

but now ...

... back to the roots !

Illustration using „Phantom“-Data

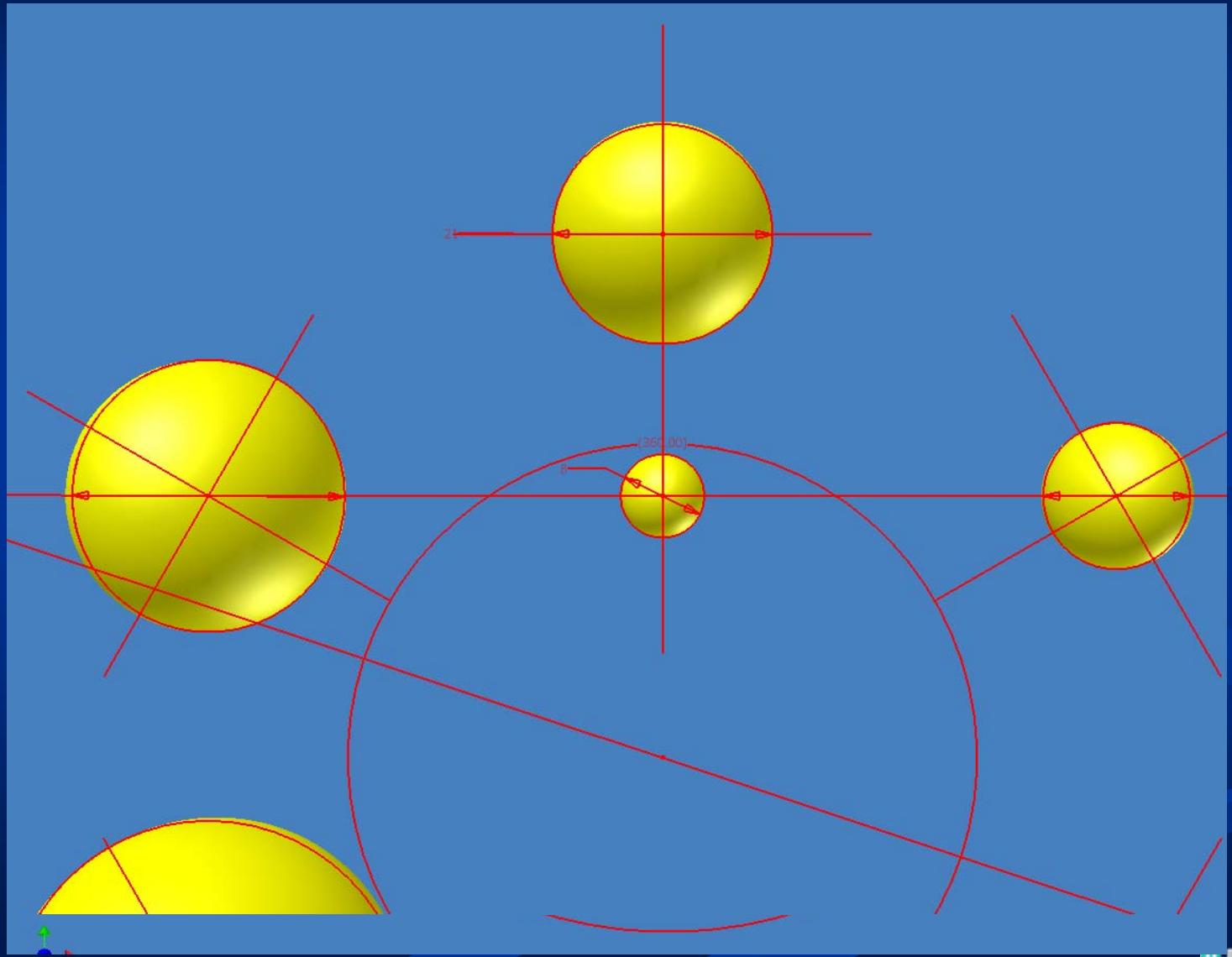
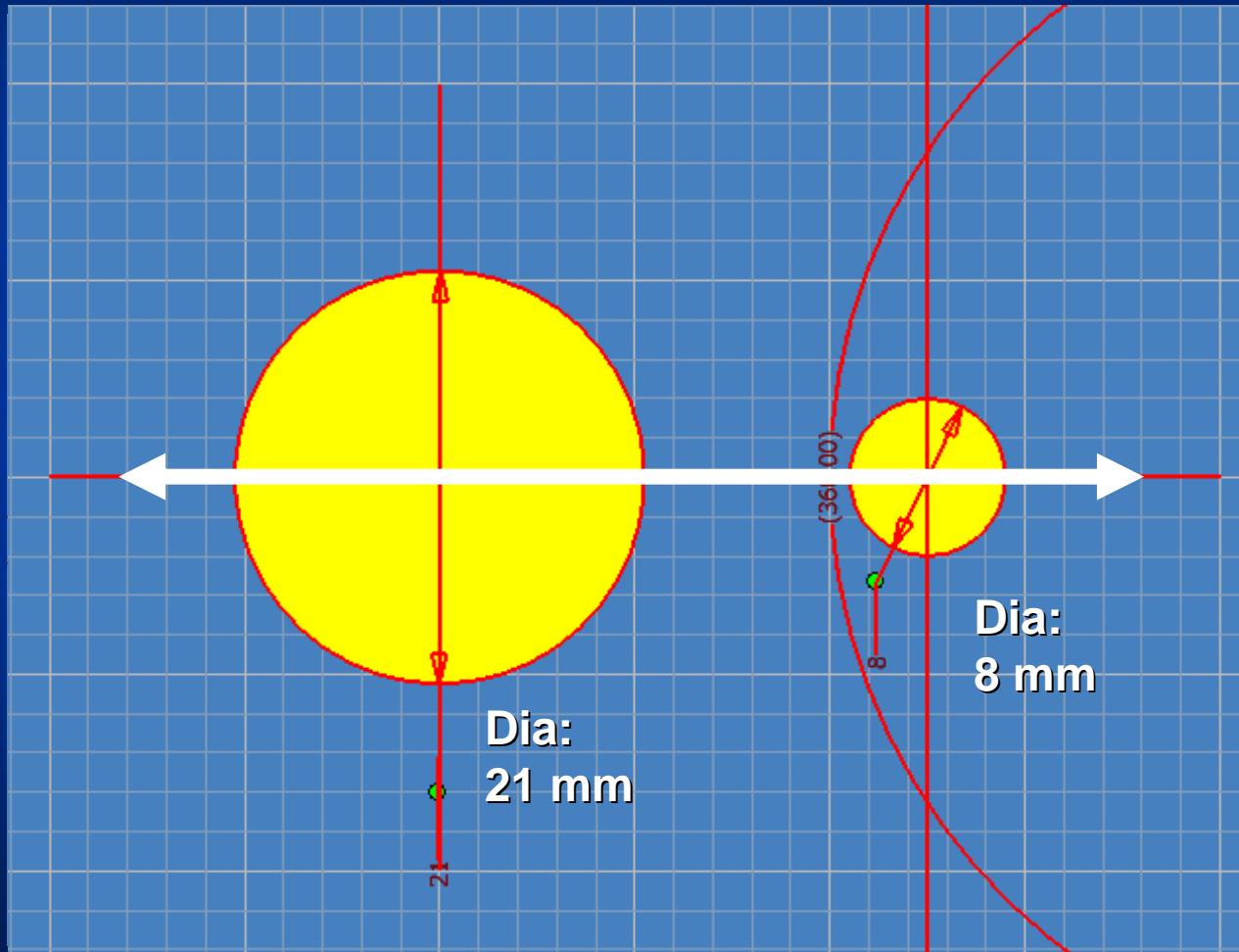
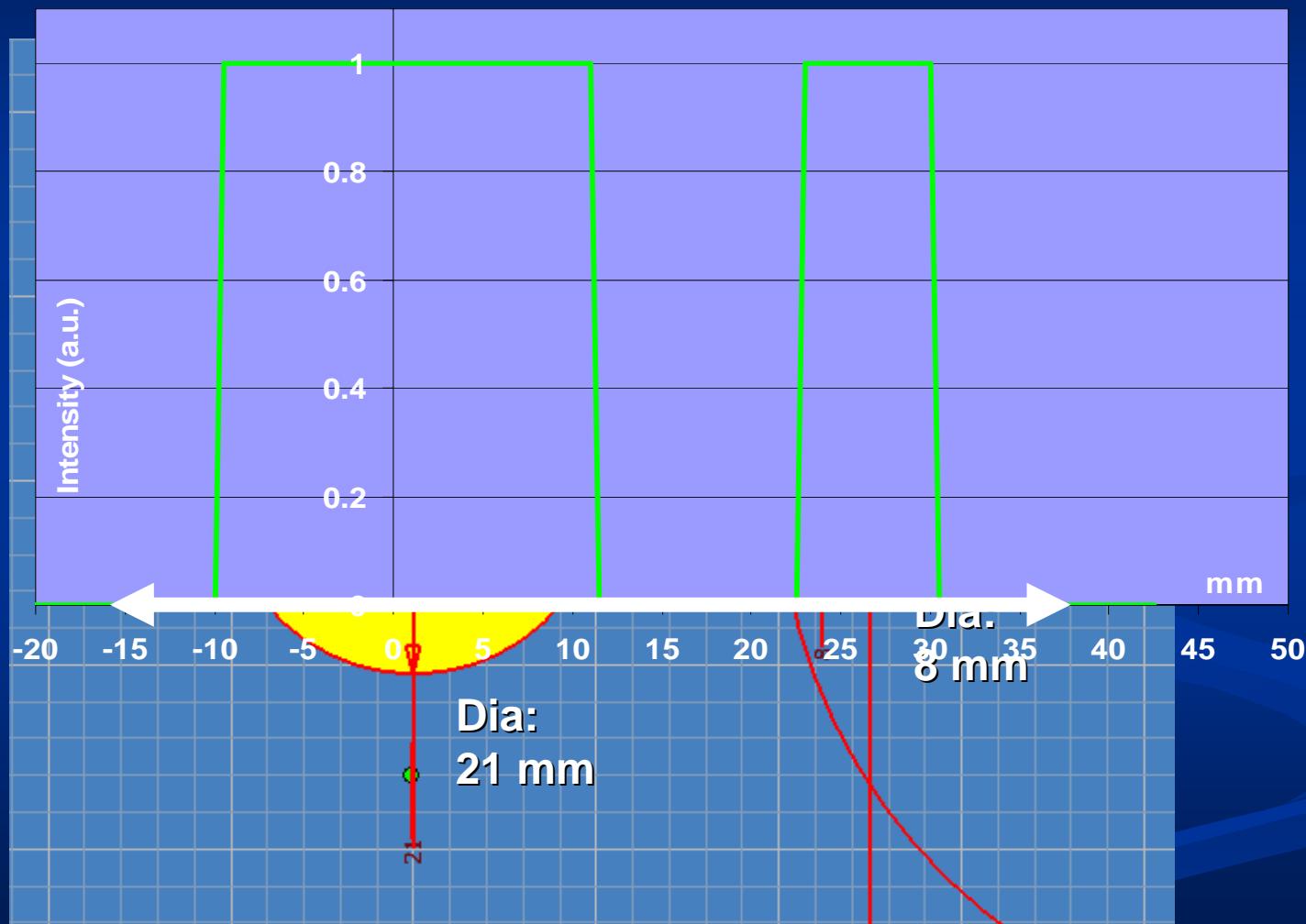


Illustration using „Phantom“-Data

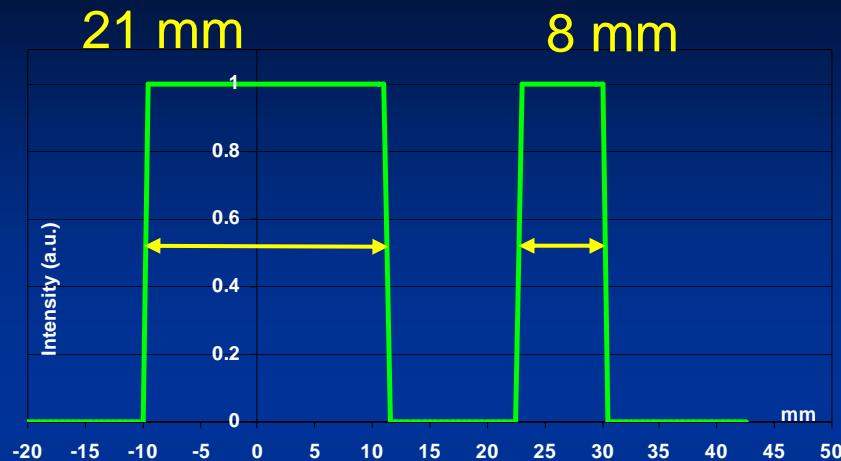


Determining Intensity



Imaging:

Object



Image



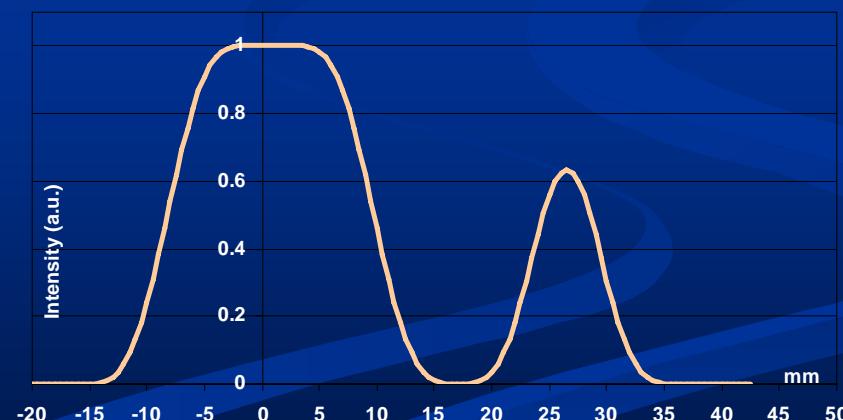
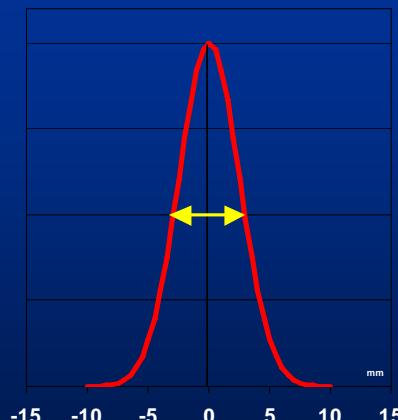
Convolution

+

Sampling

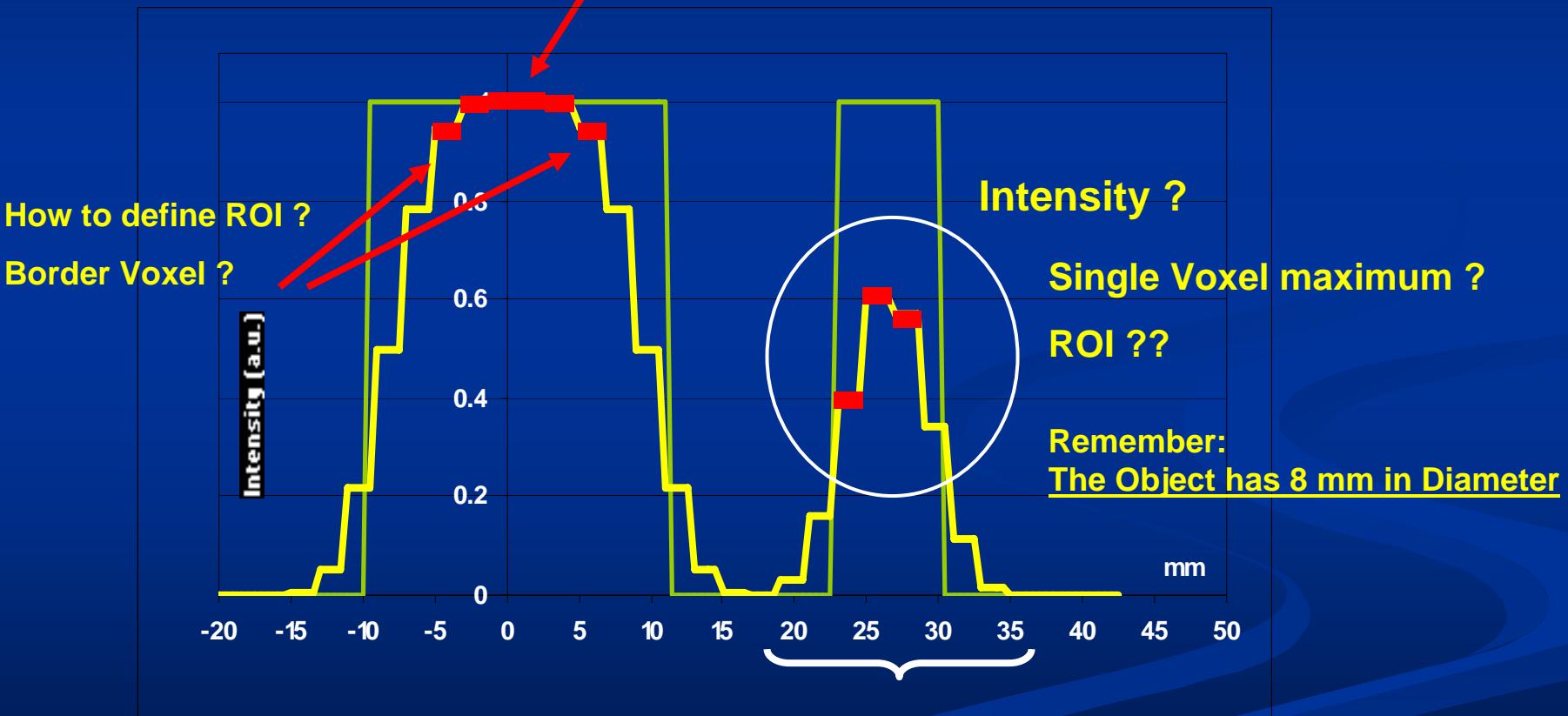
Transfer
Function

FWHM ca.
5.5 mm



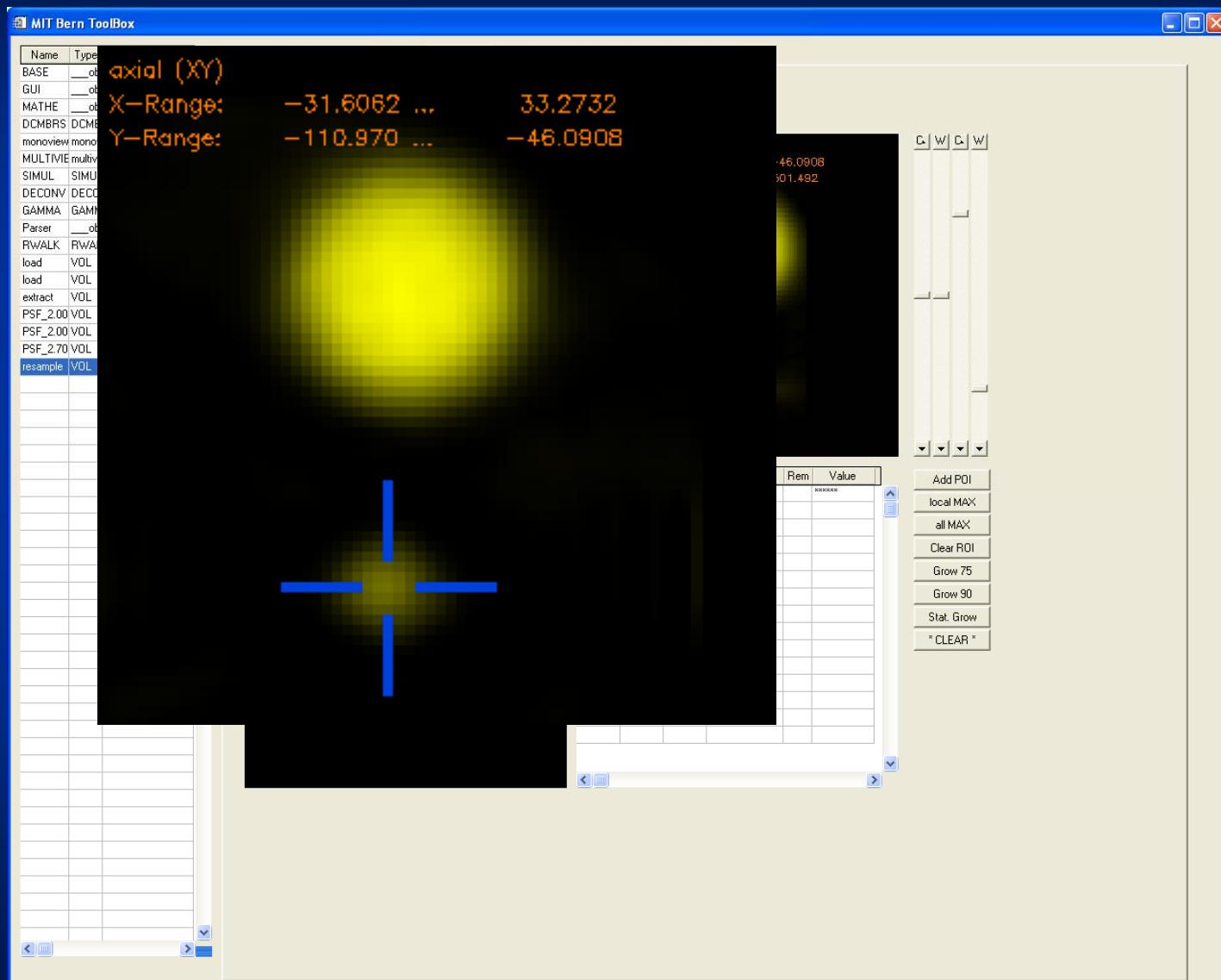
Determining Intensity

Intensity: 4 Voxel reach (almost) full intensity
-> define as ROI and calculate average to determine original intensity ...

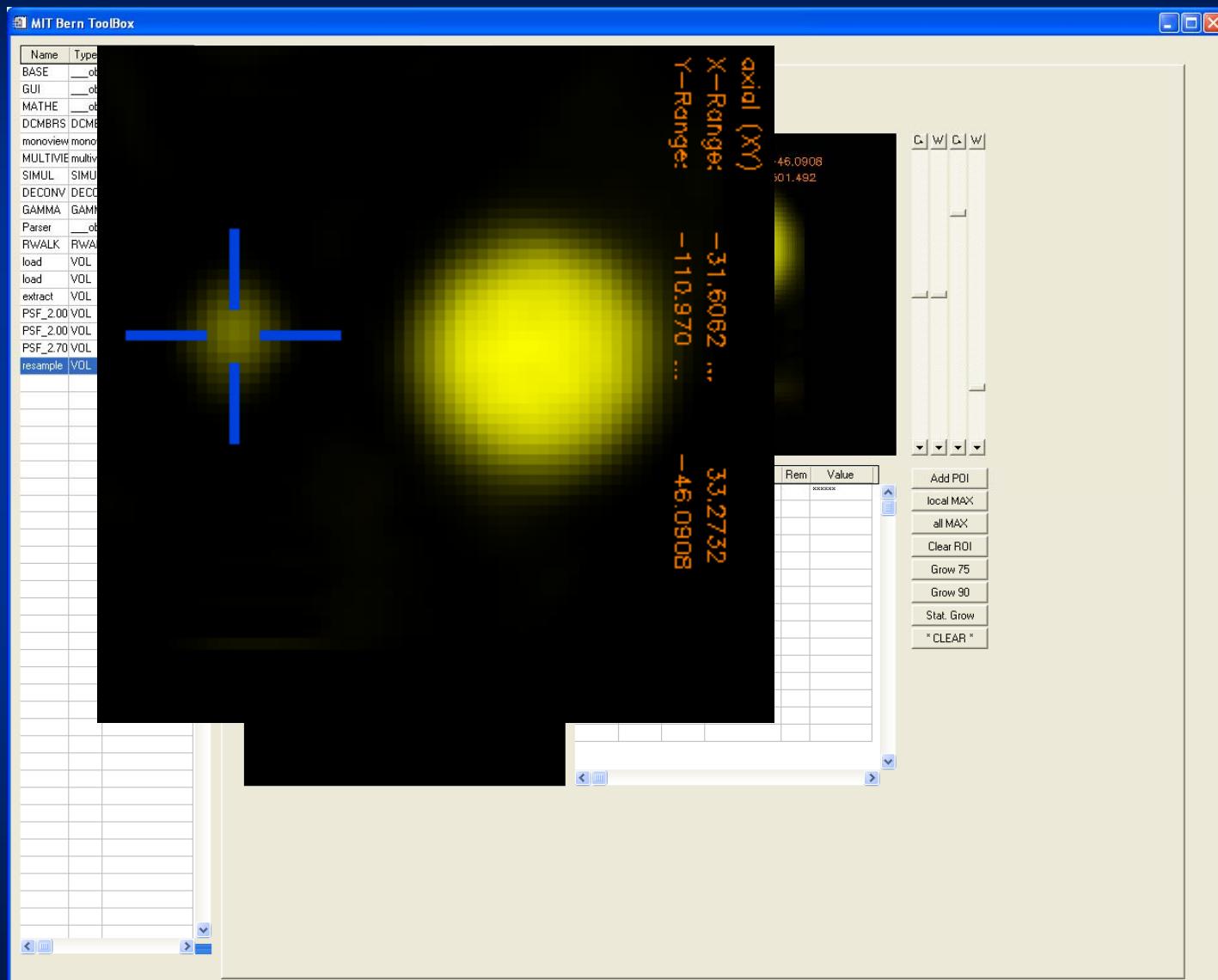


Partial volume effect: Intensity „leaks out“ to neighbouring Voxels in 3 dimensions (!) but is not lost at all ...

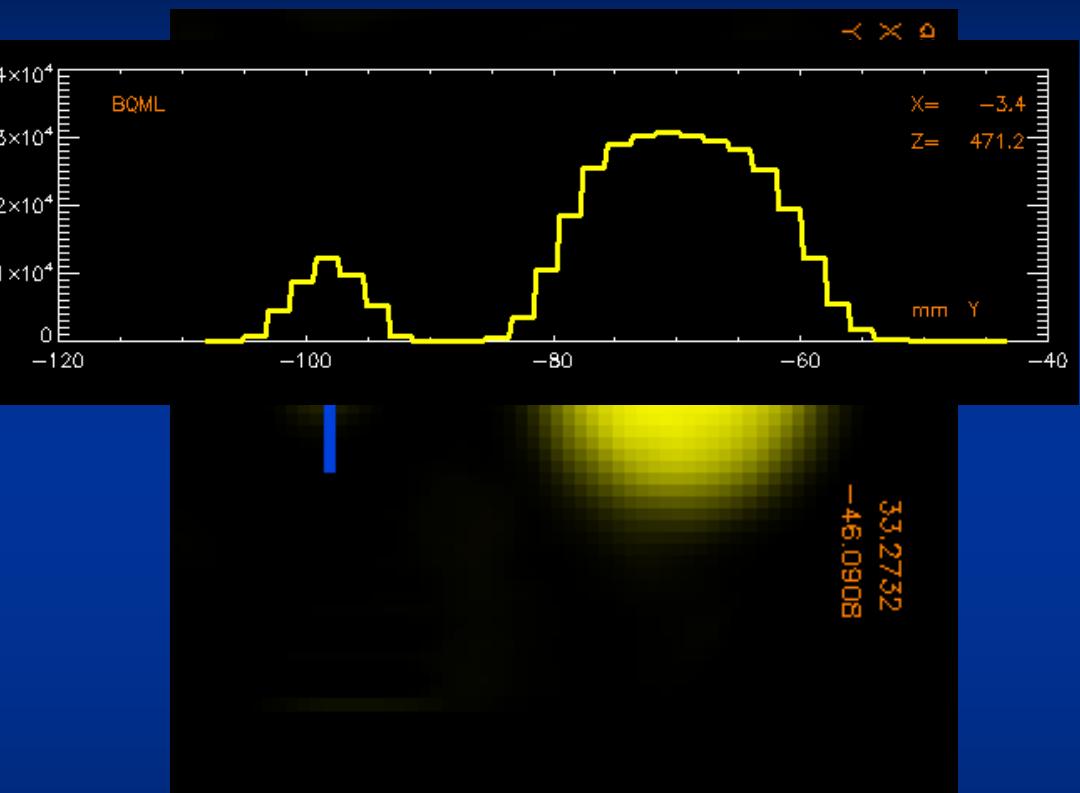
Measurement



Measurement

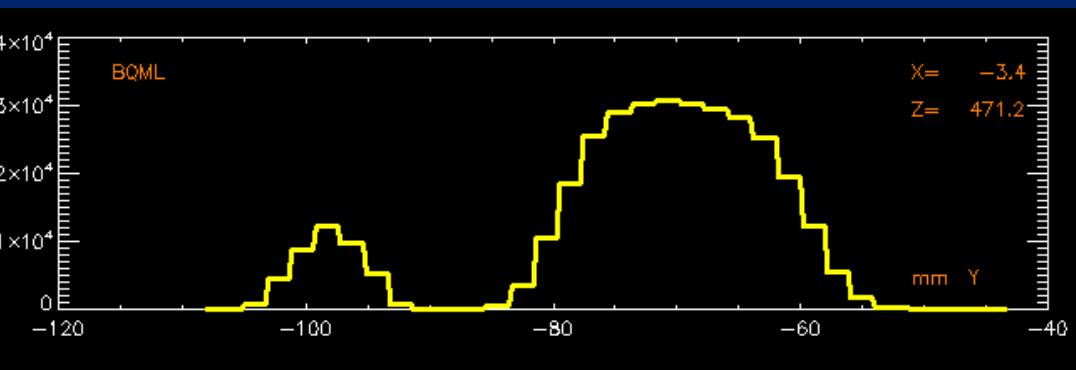


Measurement



Dia. 8 mm

Dia. 21 mm



Convolution



Deconvolution

Minimal Entropy Deconvolution

Sampling



Resampling

Fourier Transform Interpolation

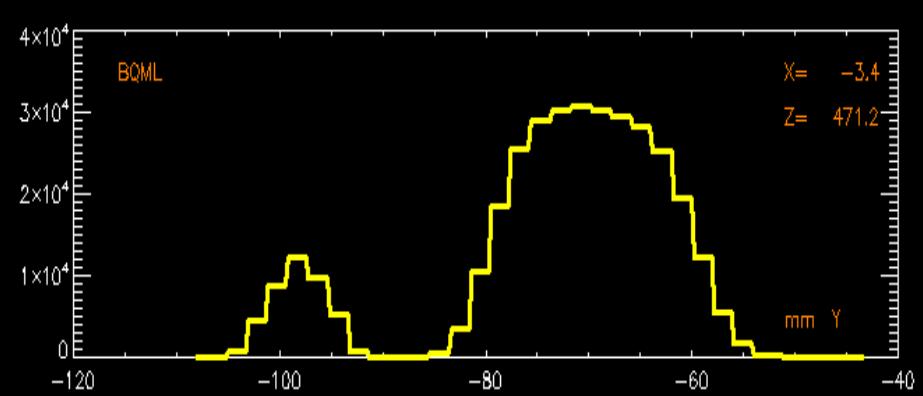
Measurement



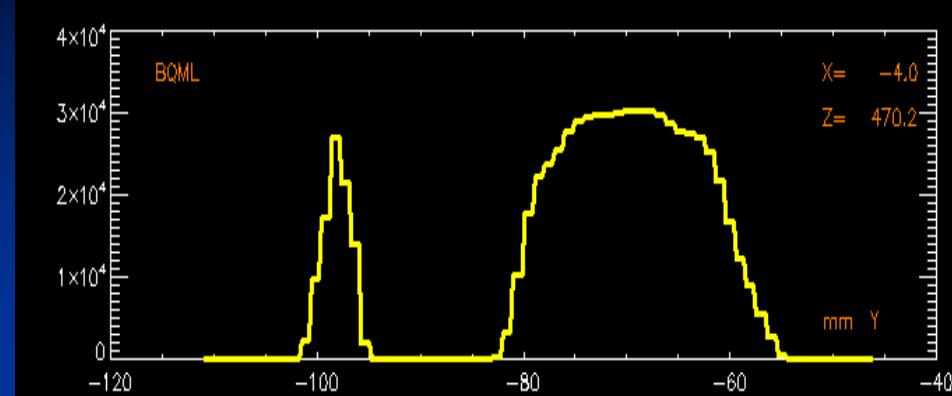
Region Growing

Statistical Region Growing

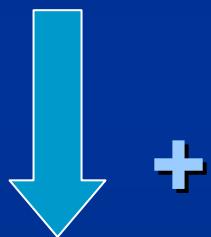
Image



Reconstructed Object

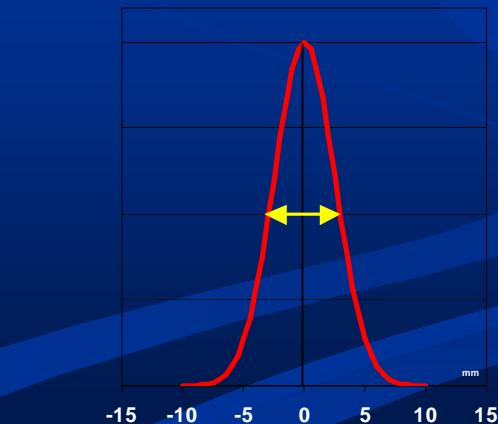
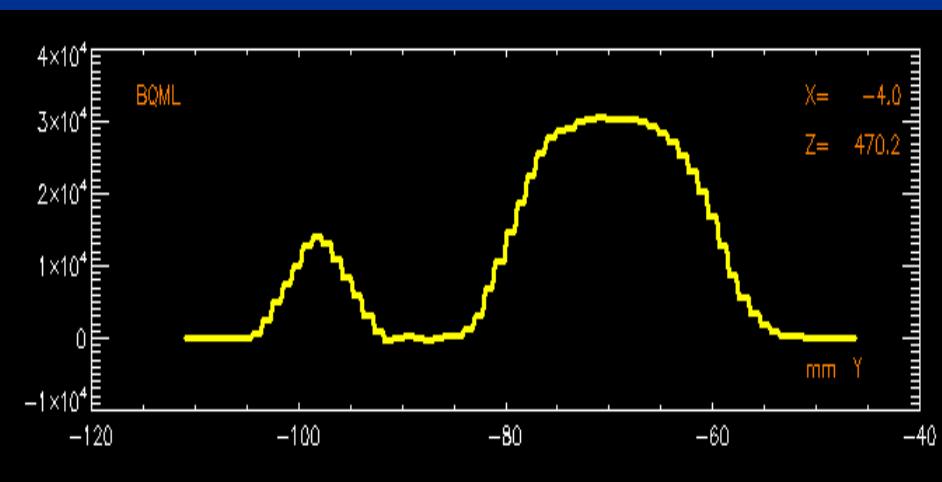


**FT Interpolation
(Resampling)**



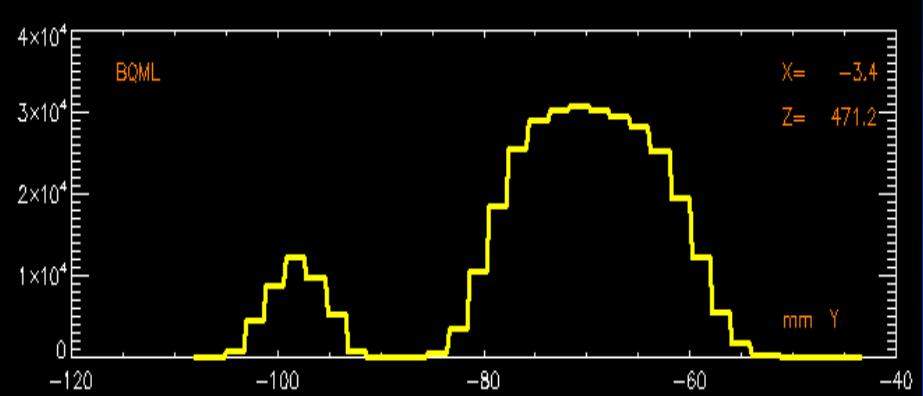
+

Deconvolution

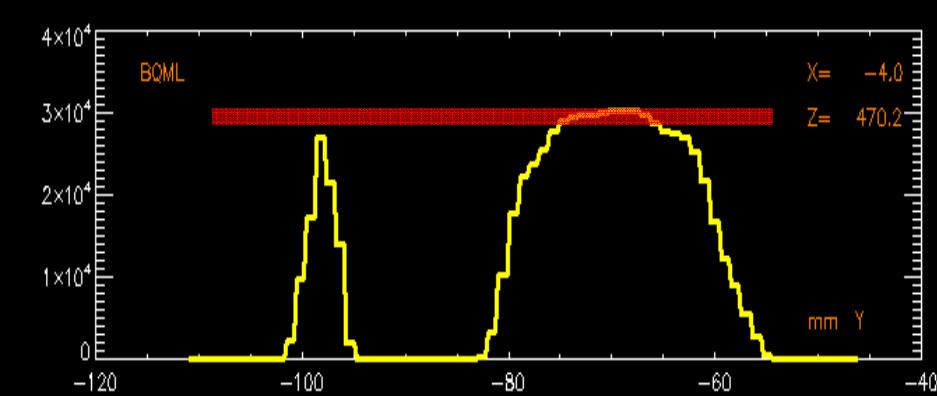


**Transfer
Function**
FWHM ca.
5.5 mm

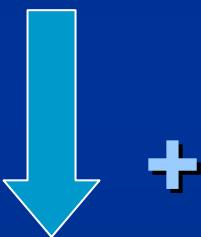
Image



Reconstruction

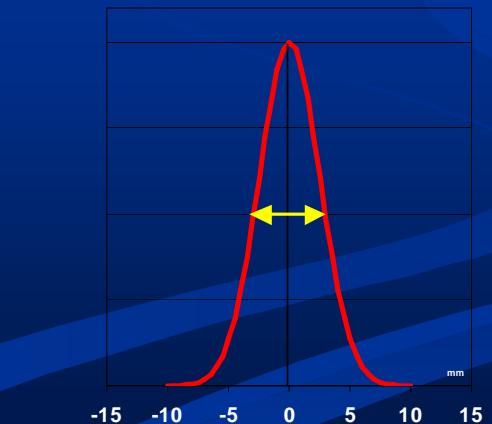
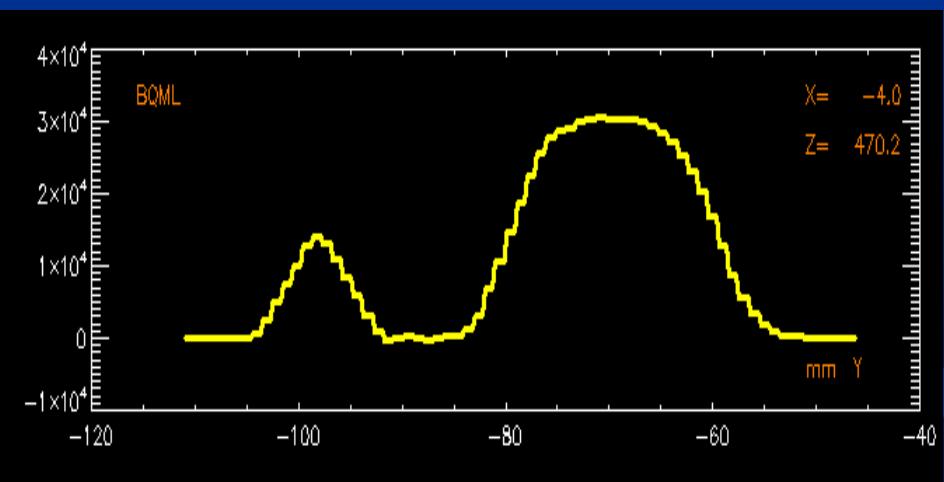


**FT Interpolation
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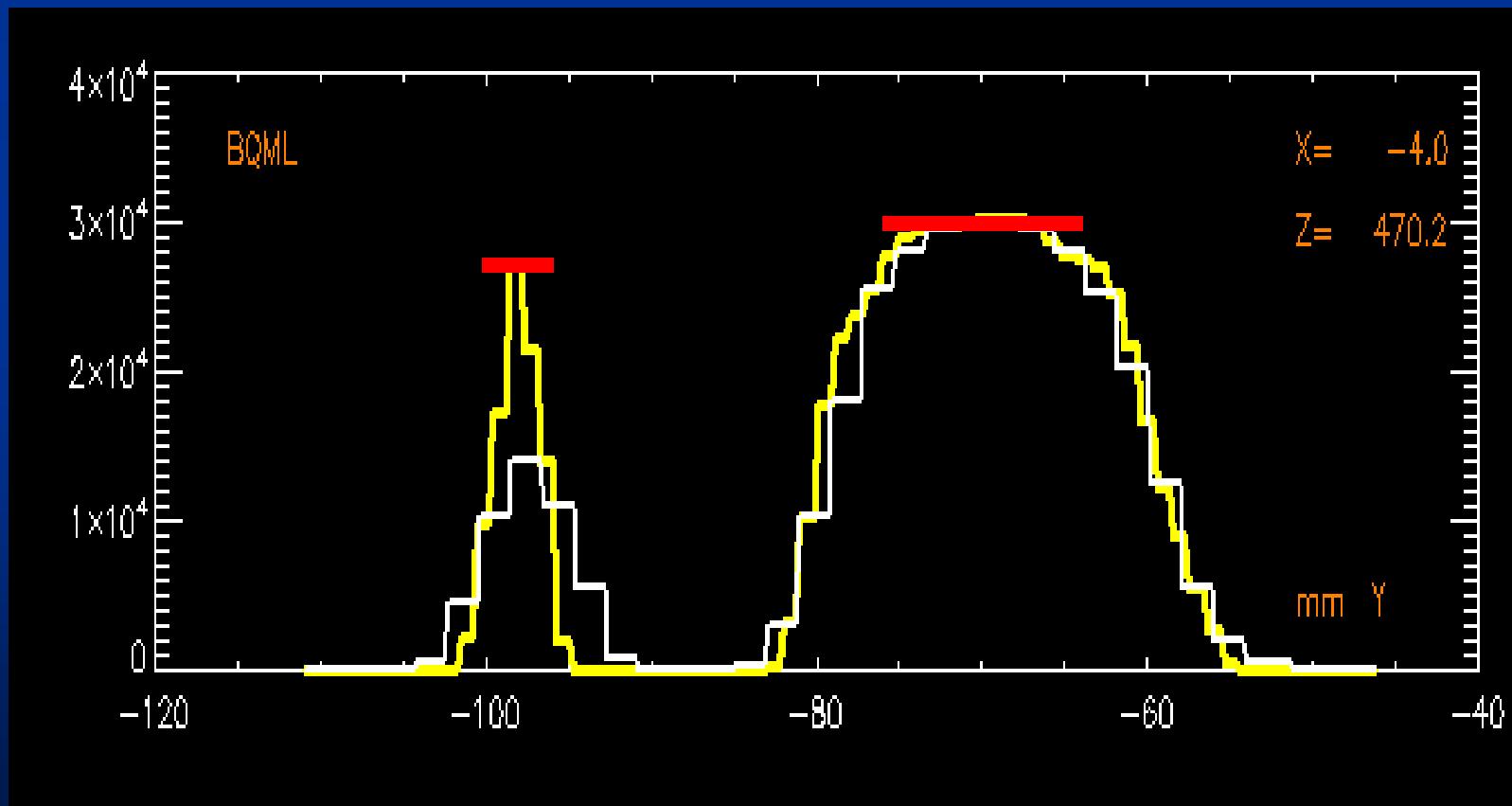


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Deconvolution



Determining Intensity



Remark:

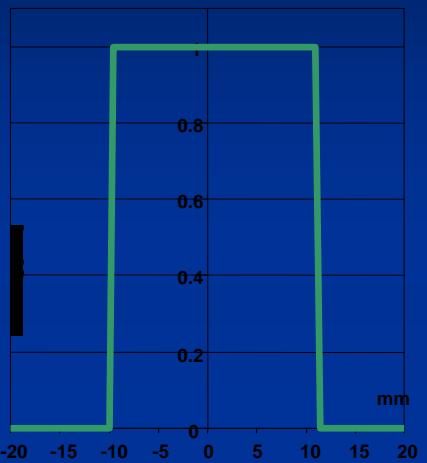
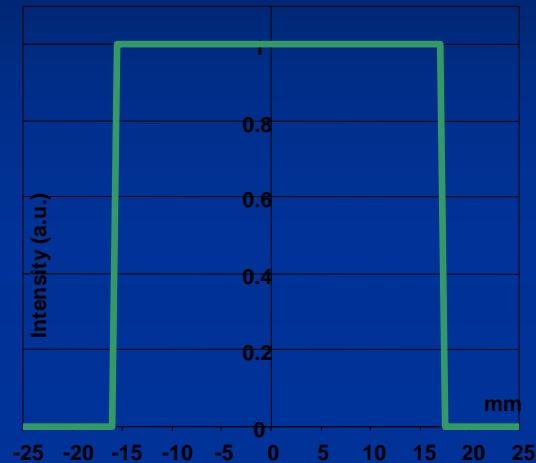
In fact the model just shown
is wrong.

A PET using iterative reconstruction algorithms,
CT based attenuation correction,
superresolution algorithms and
methods to correct for scatter ...

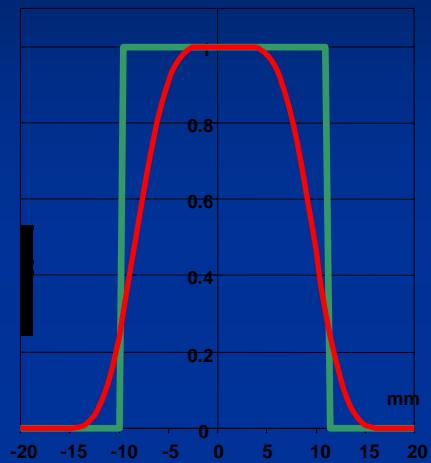
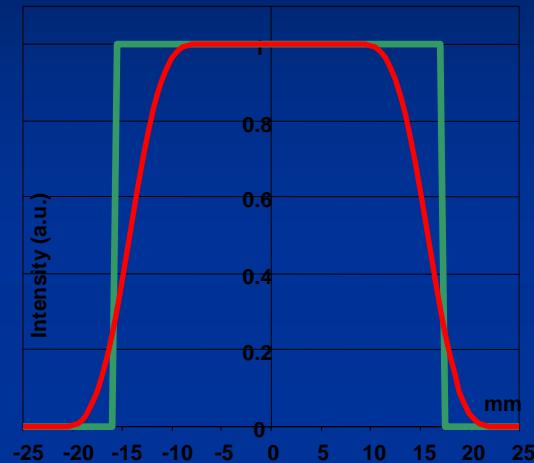
... does not have a stable transfer function.

But it looks like it would have ...

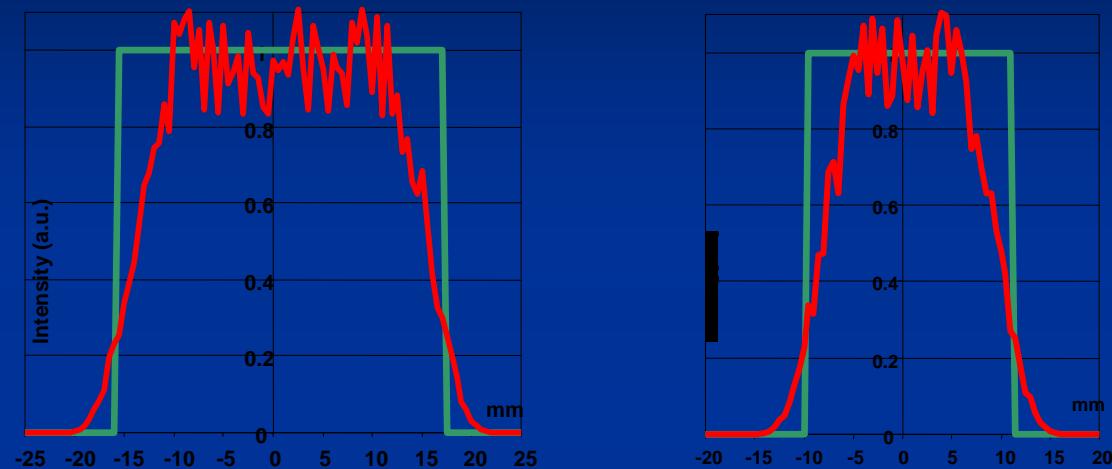
Object,



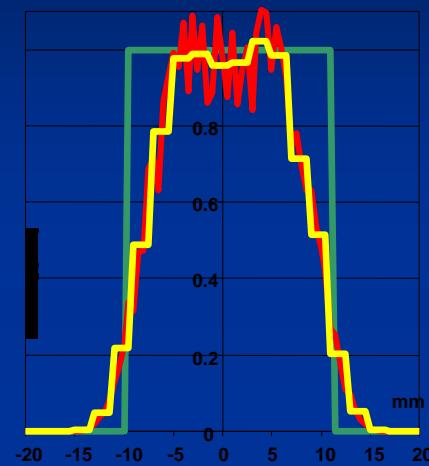
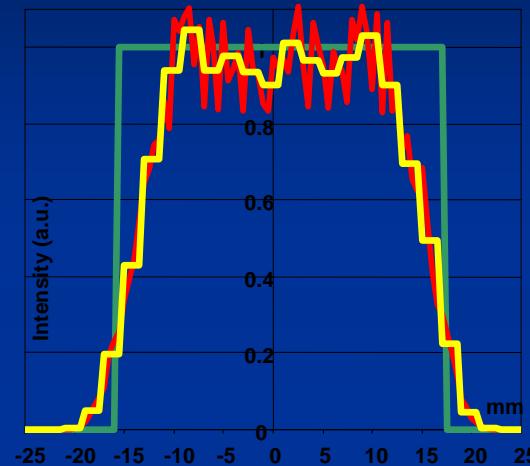
Object, Convolution,



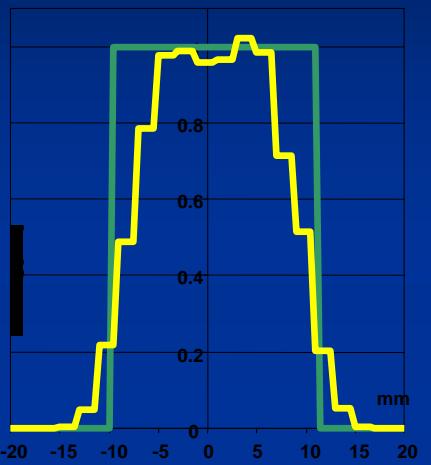
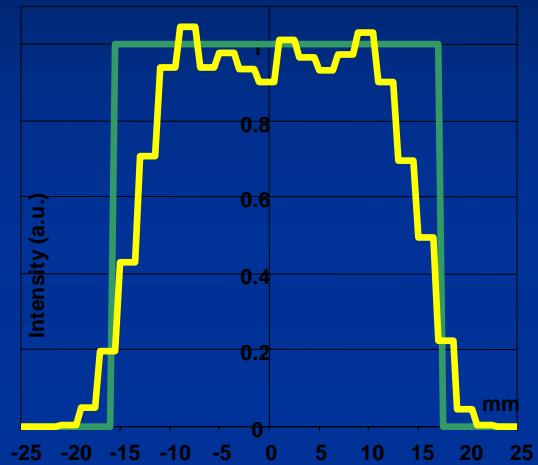
Object, Convolution, Noise,



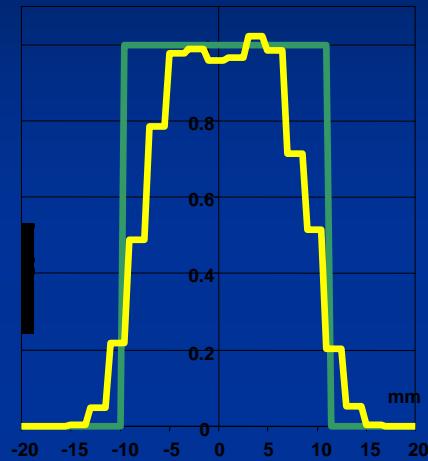
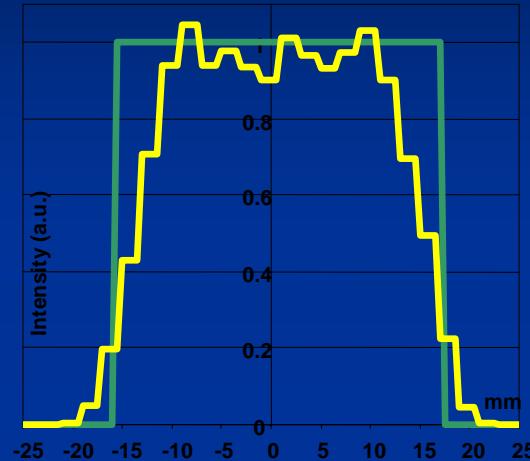
Object, Convolution, Noise, Sampling...



-> Signal

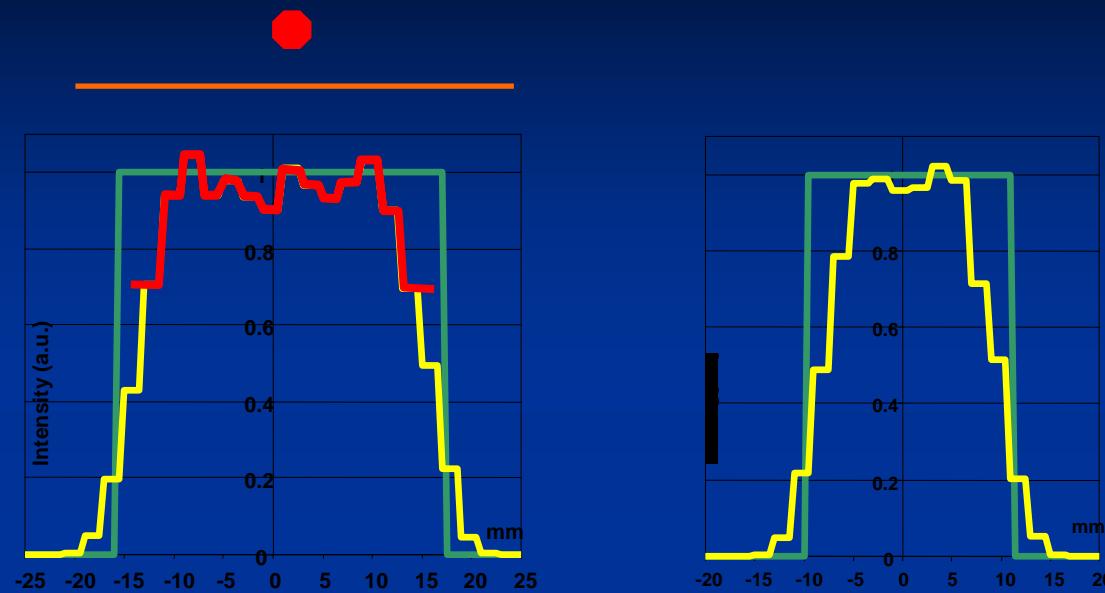


Region Growing conventional



- 1: choose a point within Region of Interest
- 2: „grow“ by including all neighbors with (e.g.) Intensity > 80%

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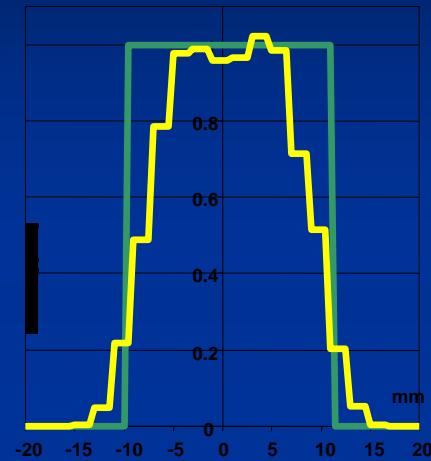
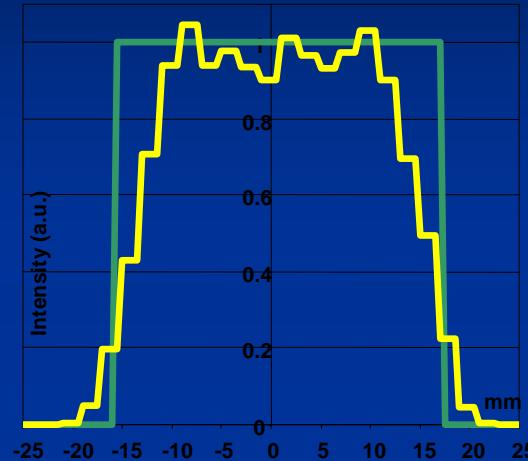


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=> (-) result depending on arbitrary starting point

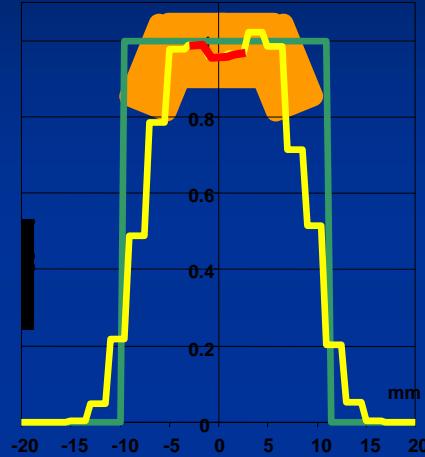
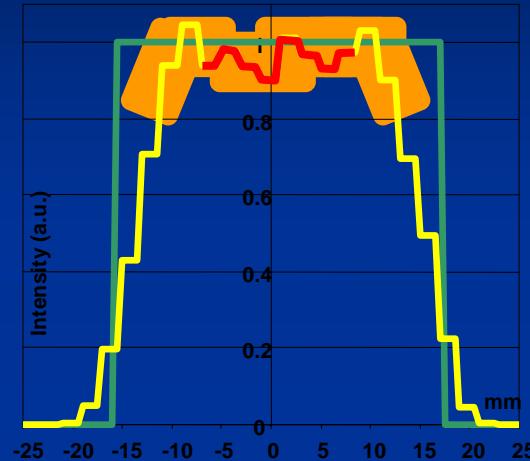
=> (-) not suitable for very small regions

Region Growing, statistical, local



- 1: choose a point within Region of Interest
- 2: „grow“ by including all neighbors having a „flat“ environment
(e.g.) standard deviation in local surrounding below a limit

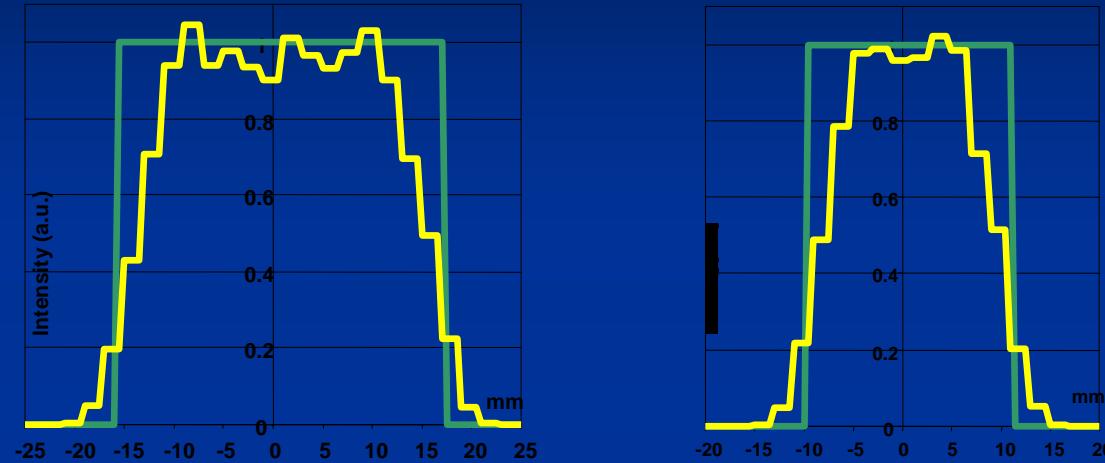
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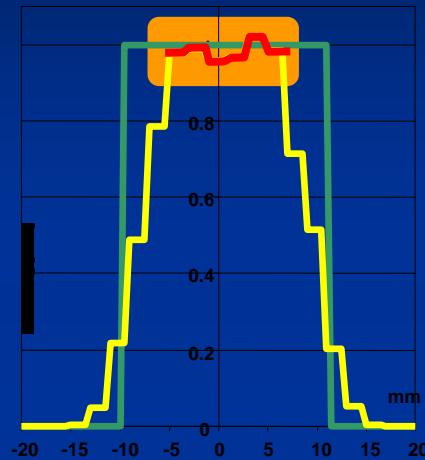
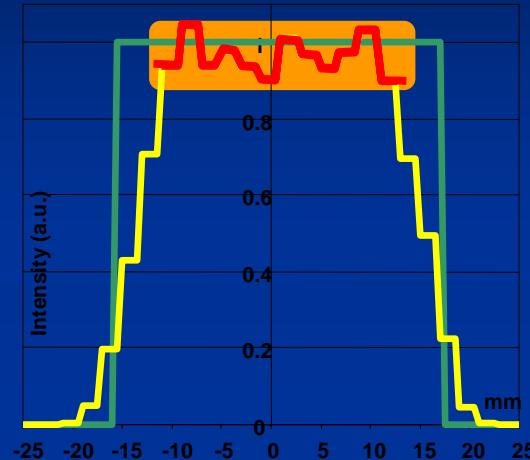
- => (+) result does not depend on starting point
- => (-) border of area is missing
- => (-) tendency to grow out of ROI via potential „smooth“ pathways

Region Growing, statistical, full region



- 1: choose a point within Region of Interest
- 2: „grow“ by including neighbors if the overall variance of the total resulting new region stays within given limit.

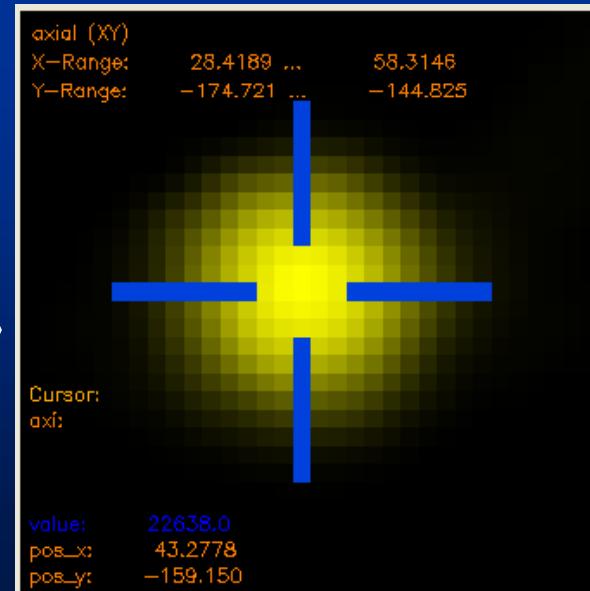
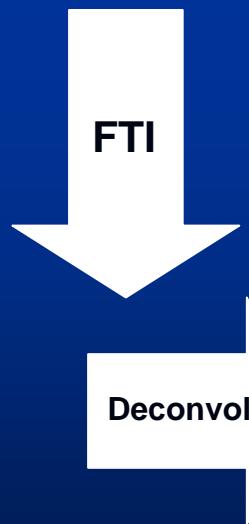
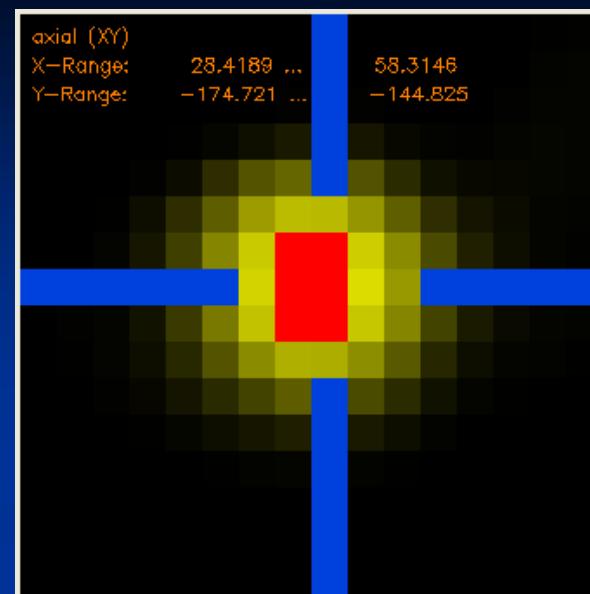
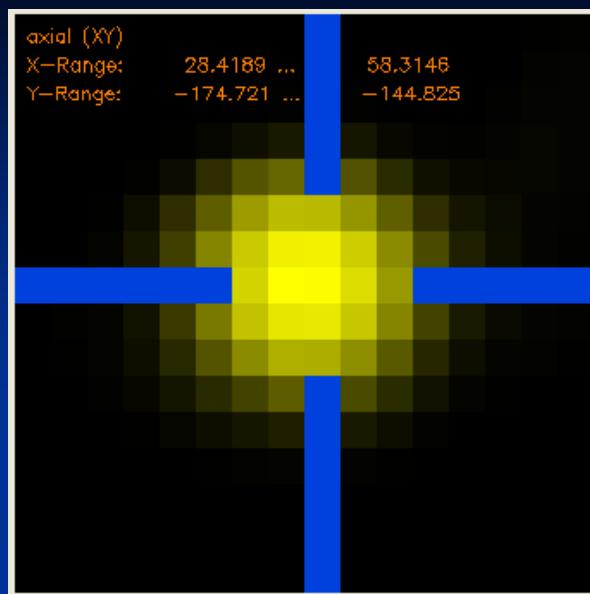
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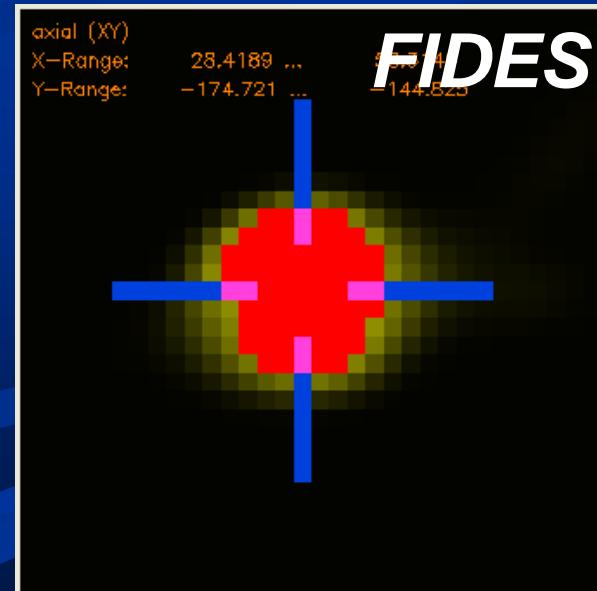
=> (+) result does not depend on arbitrary starting point

=> (+) process includes the „bordersurface“
i.e. even very small regions are captured



Stat.Grow
„0.05“

A white arrow points to the right, containing the text "Stat.Grow „0.05“", which likely refers to a statistical growth or thresholding step. The final segmented image shows a large red core surrounded by a yellow halo, identical to the result in the second panel. The word "FIDES" is printed in large white letters across the bottom right of the image.



Volume Delineation:

The simple case:

- More or less homogeneous region of interest ...
- ... inside of another more or less homogeneous region
- Region is big compared to spatial resolution and sampling period,
i.e. combined volume of „surface voxels“ is small compared to total volume of region of interest.
- Measured values inside region show a significant difference to values outside

Use one of the standard methods:

**Select a Voxel inside,
then region growing using a suitable threshold**

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The not so simple case:

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- Low signal to noise

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- artifacts

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The not so simple case:

- Low spatial resolution
- Low signal to noise
- Artifacts
- low spatial sampling frequency

Volume Delineation:

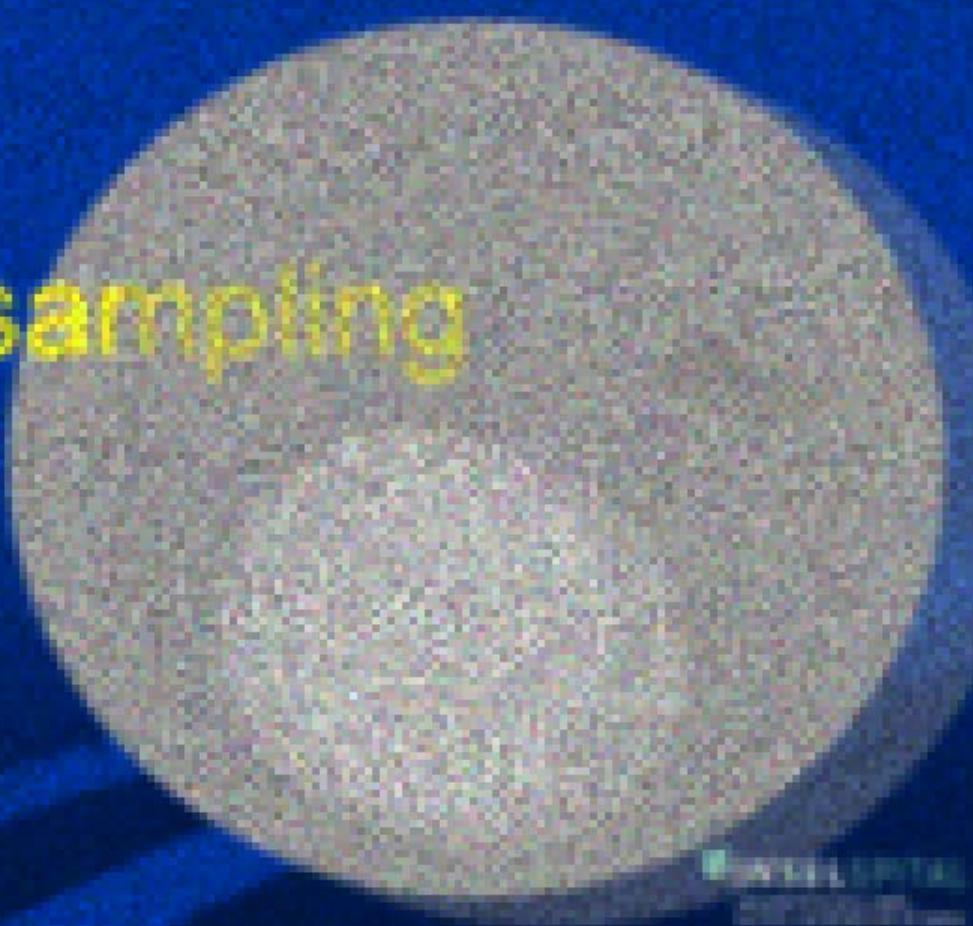
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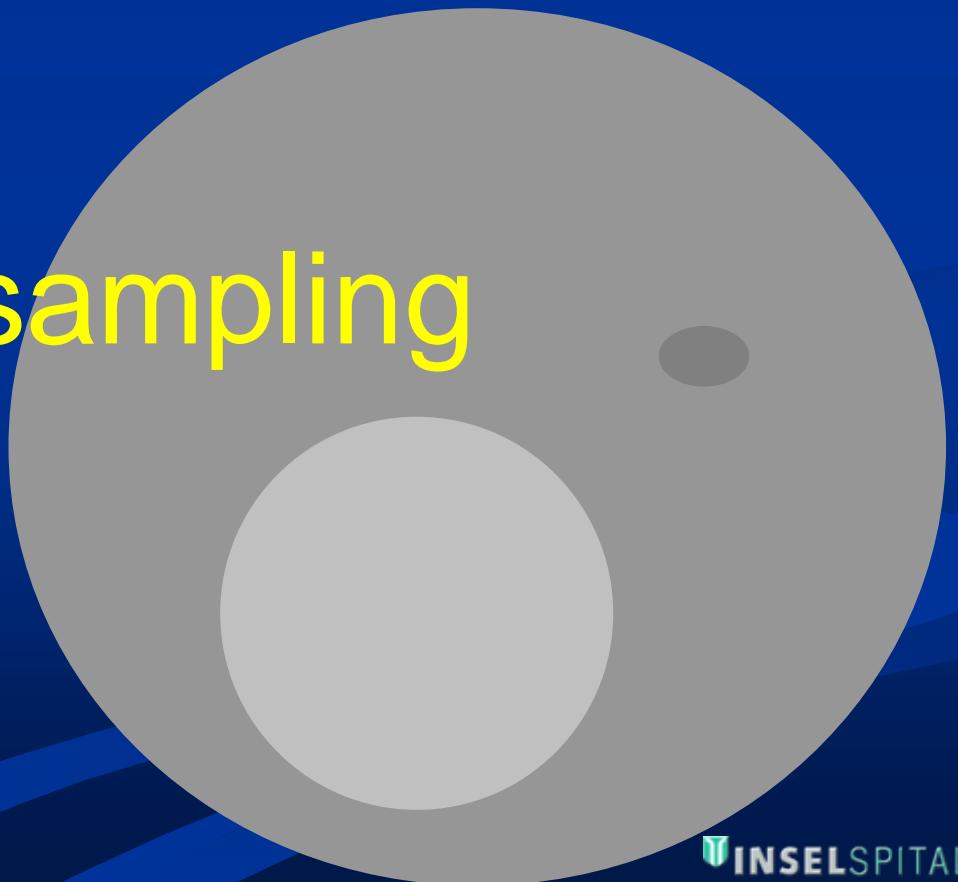
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Conclusion

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Contradiction

- Use physical and mathematical sound methods, i.e. numerical calculations, to check for validity and to improve your results

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